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NERUBATSKYI V. P., PhD, Associate Professor HORDHENKO D. A., Postgraduate Ukrainian State University of Railway Transport

Kharkiv, Ukraine

INCREASING ENERGY EFFICIENCYOF ASYNCHRONOUS ELECTRIC DRIVE BY OPTIMIZATION OF SWITCHING FREQUENCY IN FREQUENCY CONVERTER

Asynchronous electric motors are widely used in various industries and transport – from rolling mills to rail transport. Frequency converters that work with sinusoidal or spatial-vector pulse-width modulation are most often used to control the speed and torqueof induction motors [1, 2].

Improving theenergy efficiency of an asynchronous electric driveis an important area of development of electrical engineering and electromechanics [3, 4]. Theincrease in the efficiency of induction motors is associated with an increase in the poles of induction motors, a decrease in the resistance of the windings and an increase in the power factor. In addition, to ensure the maximum efficiency of the induction motor, it is rational to use an induction motor with full (nominal) load (Fig. 1).

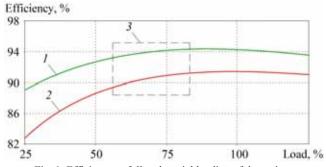


Fig. 1. Efficiency at full and partial loading of theengine: *I*– high-efficiency electric motor; 2–inefficient electric motor; 3– fixed zoneof normal speed

It is also important to increase the efficiency of frequency converters in an asynchronous electric drive [5, 6]. Types of power losses in power switches and possible methods of reducing these losses are given in Table 1.

Table 1 – Structural and circuit methods to reduce power losses in the power switches of theinverter

Type of	Components of	Causes of	Possible	Disadvantages
losses	losses	losses	methods to	
			reduce losses	
Static	– losses in the	- depending	- changeof an	- high cost of
	leading state;	on theamount	internal design	switches based
	– leakage	of current and	of a power	on silicon
	currents	voltageon the	switch for	carbide
		device	decreasein	
			voltage drop	
Dynamic	- transistor	- theamount	- soft switching	-complications
	switching	of current and	methods;	of device
	losses;	voltage during	improved	circuitry;
	- losses on	switching;	driver designs;	- increasein
	switching off	duration of	reducing the	cost;
	the transistor;	switching;	switching	– reducing the
	- diode	– number of	frequency	quality of
	recovery losses;	switches		theoutput
	– losses in			current of
	drivers			theinverter

Reduction of power losses and, accordingly, increase of efficiency in the system "frequency converter –asynchronous motor", in addition to design methods, can beachieved by algorithmic methods, ie features of the algorithm of control systems, or mode of operation [7].

Most common frequency converters (such as Siemens, OWEN, Danfoss and others) have theability to configureand set the modulation frequency. The switching frequency affects the following factors. As the modulation frequency increases, the power losses in the power switches of the stand-aloneinverter increase. At the same time, as the switching frequency increases, the sinusoidality of theinverter phase current improves, as a result of which additional power losses in the windings of induction motors from higher harmonics are reduced. Oneof the ways toimprove theenergy efficiency of an asynchronous electric drive with a frequency converter is tooptimize the switching frequency of power switches. There is a dilemma, the higher the switching frequency of the transistors, the greater the power loss in the power switches, but the higher the sinusoidal current of theinduction motor and, accordingly, the smaller the power loss in theinduction motor from higher harmonics. The theoretical dependences of power losses in an induction motor and a frequency converter inverter are shown in Fig. 2.

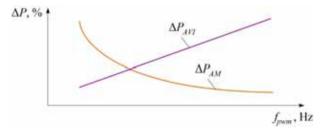


Fig. 2. Theoretical dependences of power losses in the motor P_{AM} and inverter P_{AVI} on the modulation frequency

Thus, there is a theoretically possible switching frequency at which the total power loss in the motor and inverter will be minimal.

Power losses in power MOSFET or IGBT modules consist of power losses in the transistors themselves and power losses in the reverse diode. In this case, the power losses are conventionally divided into static power losses – losses in the conductivestate, and dynamic power losses – losses when turning on and off the transistor. Determination of power losses in the power switches of theinverter can be determined, for example, by calculation in specialized programs from manufacturers of power transistors, namely programs MelcoSim, SemiSel, etc.

A method for determining additional heat losses in the windings of electric motors of alternating current from higher harmonics, which are uniquely determined based on the resulting value of the coefficient of harmonic distortion of the motor current. This method can be used in the case when the effect of the skin effect on the resistance of the windings of motors with a limited range of higher harmonics of the current is insignificant. In this case, the additional losses in the windings from the higher harmonics can be calculated based on the increase in the root mean square value (*RMS*) of the current relative to the value of the first harmonic, and hence the increase in square losses depending on the RMS value of the current. The effective value of alternating (or constant pulsating) current is equal to the value of such direct current, which for a time equal to one period of alternating current, will do the same work (thermal or electrodynamic effect) as the considered alternating current.

Simulation of system "autonomous voltage inverter – asynchronous motor operation is performed at nominal engine load (nominal constant torqueand nominal speed). During the experiments, only the PWM modulation frequency and, accordingly, the switching frequency of the power switches changed. According to the simulation results, the value of the first harmonic of theoutput voltageand output current does not change due to the change of modulation frequency, but the content of higher harmonics decreases with increasing PWM frequency, as a result of which the rms value of phase current.

During theimplementation of an autonomous inverter, a power transistor of the PS21A79 typeand a typical asynchronous electric motor with a pull of 3.7 kW with an optimal modulation frequency in PWM a frequency of 1200 Hz. At the same time, it means that in the rangeof frequencies from 1 kHz to 2 kHz, the total volumeof theeffort does not grow. In the frequency ranges below 1 kHz and more than 2 kHz, it is difficult to grow.

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СУМЦОВ А. Л., к.т.н., доцент ї МАКСИМОВ М. В., асистент КЛИМЕНКО О. В., ст. викладач

Український державний університет залізничного транспорту

Харків, Україна

ЗАГАЛЬНА ІСТОРИЧНА ОЦІНКА КОЕФІЦІЄНТА КОРИСНОЇ ДІЇ ЛОКОМОТИВІВ

Локомотивобудування має досить довгу та цікаву історію. Перший прототип паровоза було збудовано ще у Франції в 1769 році інженером Ніколя-Жозе Кюньо. Перший рейковий паровий локомотив було розробив у 1801 році британець Ричардом Тревесік. З того часу було розроблено досить багато типів локомотивів, які мають суттєво різні технічні показники.